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Discipline: Mechanical	Semester: 5th Sem	Name of the Teaching Faculty: SRI SIDDHARTHA MEHER
Engg.		
Subject: Mechatronics	No. Of Days/Week	No. Of Weeks: 15
	Class Allotted	
Week	Class Day	Theory/Practical Topics
lst	1st	INTRODUCTION TO MECHATRONICS: Definition, Advantages & disadvantages of Mechatronics.
	2nd	Application of Mechatronics, Importance of mechatronics in automation.
	3rd	Components of a Mechatronics System
	4th	Review class and Discussion
2nd	lst	Assignment Evaluation & Class Test
	2nd	SENSORS AND TRANSDUCERS:
		Definition and classification of transducer
	3rd	Classification of Transducer
	4th	Electromechanical Transducers
3rd	1st	Transducers Actuating Mechanisms
	2nd	Sensors and its classifications
	3rd	Displacement & Positions Sensors
	4th	Electromechanical Transducers
4th	1st	Transducers Actuating Mechanisms
	2nd	Sensors and its classifications
	3rd	Displacement & Positions Sensors
	4th	Velocity and Motion sensors
5th	lst	Force and Pressure sensors.
	2nd	Temperature sensors
	3rd	Light sensors
	4th	Review class and Discussion
6th	lst	Assignment Evaluation & Class Test
	2nd	ROBOTICS: Definition, Function and laws of robotics

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		3rd	Types of industrial robots, Advantages, Disadvantages and Applications of robots
		4th	Robotic systems
th	A BOOK COMMAND OF THE PARTY OF	· 1st	Review class and Discussion
		2nd	Assignment Evaluation & Class Test
		3rd	ELEMENTS OF CNC MACHINES: Introduction to Numerical Control of machines
		4th	NC machines
Bth		lst	CNC machine
		2nd	CAD and CAM
	14 a 12 a	3rd	Software and hardware for CAD/CAM, Functioning of CAD/CAM system
		4th	Features and characteristics of CAD/CAM system, Application areas for CAD/CAM
9th		1 st	Review class and Discussion
	5 , 1 mm 2 - 10 mm 1 - 11	2nd	Introduction to CNC Machines, Elements of CNC machines
	1	- 3rd	Machine Structure
		4th	Guideways/Slide ways and its types
10th			Drives and types, Spindle drives
		2nd	Feed drive
		- · · 3rd	Spindle and Spindle Bearings
		4th	Review class and Discussion
11th	1	Ist	Assignment Evaluation & Class Test
		2nd	PROGRAMMABLE LOGIC CONTROLLERS(PLC):
	1	3rd	Introduction, Definition and Advantages of PLC, Selection and uses of PLC
	*	4th	Architecture basic internal structures
12th	-	lst	Input/output Processing and Programming
		2nd	Mnemonics, Master and Jump Controllers
		3rd	Review class and Discussion
		4th	Assignment Evaluation & Class Test
13th		lst	MECHANICAL ACTUATORS:
12011		2nd	Machine, Kinematic Link, Kinematic Pair
		3rd	Mechanism, Slider crank Mechanism
		4th	Gear Drive, Spur gear, Bevel gear, Helical gear, worm gear
14th		1 st	Belt & Belt drive
1-1111		2nd	Electrical Actuator: Switches and relays, Solenoids
		3rd	D.C Motors

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	4th	A.C Motors
15th	lst	Stepper Motors, Specification and control of stepper motors
	2nd	Servo Motors D.C & A.C
	3rd	Review class
	4th	Assignment Evaluation & Class Test

Signature of faculty

Signature of HOD